

# Tb Mechanics Edition 2b Pages 344 Code 1210 Concept Theorems Derivation Solved

Tb Mechanics Edition 2b is a comprehensive textbook covering the principles of mechanics and their applications. It is designed for undergraduate students of engineering and science who have a basic understanding of mathematics and physics. The book is divided into two parts, with the first part covering the fundamentals of mechanics and the second part covering more advanced topics. This article will provide an overview of the book's content, focusing on the concepts, theorems, derivations, and solved problems presented in pages 344-345, which are identified by the code 1210.

## Concept: Moment of Inertia

The concept of moment of inertia is introduced in page 344. It is defined as a measure of the resistance of an object to angular acceleration. The moment of inertia depends on the mass of the object, its distribution, and the axis of rotation. The book provides formulas for calculating the moment of inertia of various shapes, including rectangular, cylindrical, and spherical objects.



## TB Mechanics I Edition-2B I Pages-344 I Code-1210 | Concept+ Theorems/Derivation + Solved Numericals + Practice Exercise | Text Book by A.R. Vasishtha

★★★★☆ 4 out of 5

Language : English

File size : 6935 KB

Screen Reader : Supported

Print length : 219 pages

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Shape	Schematic diagram	Moment of inertia
Rectangle		$I_{X_1} = \frac{1}{12}bh^3$ $I_{X_2} = \frac{1}{12}b^3h$ $I_{X_1} = I_{X_2} = \frac{1}{12}bh^3$ $I_C = \frac{1}{12}bh(b^2 + h^2)$
Triangle		$I_{X_1} = \frac{1}{36}bh^3$ $I_{X_2} = \frac{1}{12}bh^3$
Circle		$I_{X_1} = I_{X_2} = \frac{1}{4}\pi r^4$ $I_O = \frac{1}{2}\pi r^4$
Semicircle		$I_{X_1} = I_{X_2} = \frac{1}{8}\pi r^4$ $I_O = \frac{1}{4}\pi r^4$
Quarter circle		$I_{X_1} = I_{X_2} = \frac{1}{16}\pi r^4$ $I_O = \frac{1}{8}\pi r^4$
Elliptic		$I_{X_1} = \frac{1}{4}\pi ah^3$ $I_{X_2} = \frac{1}{4}\pi a^3h$ $I_O = \frac{1}{4}\pi ab(a^2 + b^2)$

### Theorem: Parallel Axis Theorem

The parallel axis theorem is presented on page 344. This theorem states that the moment of inertia of a body about an axis parallel to its centroidal axis is equal to the moment of inertia about the centroidal axis plus the

product of the mass of the body and the square of the distance between the two axes.

$$I = I_c + Md^2$$

where:

- $I$  is the moment of inertia about the parallel axis
- $I_c$  is the moment of inertia about the centroidal axis
- $M$  is the mass of the body
- $d$  is the distance between the two axes

### **Derivation: Moment of Inertia of a Rectangular Area**

The derivation of the moment of inertia of a rectangular area is presented on page 345. This derivation involves integrating the mass of the rectangular area over its area and multiplying the result by the square of the distance from the centroidal axis to the differential area element.

$$I = \int_A \rho x^2 dA$$

where:

- $I$  is the moment of inertia about the centroidal axis
- $\rho$  is the mass density of the rectangular area
- $x$  is the distance from the centroidal axis to the differential area element
- $dA$  is the differential area element

## Solved Problems

Several solved problems are presented on pages 344-345 to illustrate the concepts and theorems discussed in the chapter. These problems cover a variety of topics, including:

- Calculating the moment of inertia of a rectangular area
- Applying the parallel axis theorem to determine the moment of inertia of a body about a different axis
- Using the moment of inertia to calculate the angular acceleration of a body subjected to a torque

The content covered in pages 344-345 of Tb Mechanics Edition 2b provides a solid foundation for understanding the principles of mechanics and their applications. The concepts of moment of inertia and the parallel axis theorem are essential for analyzing the motion of rigid bodies, and the solved problems demonstrate how these concepts can be applied to practical engineering problems.



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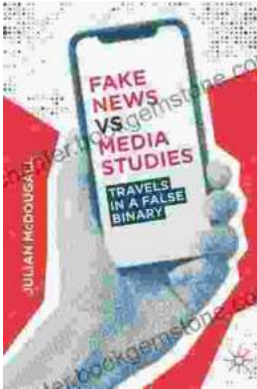
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